

Learning Driven Product Lifecycle for Automated Driving Systems

Marcus Nolte, Institute of Control Engineering, TU Braunschweig

Based on: M. Haiber; T. Brade; T. Hoffmann; C. Lalitsch-Schneider; M. Nolte; J. Pott:
„Lerngetriebener Produktlebenszyklus für hochautomatisierte Fahrzeuge“,
Tag des Systems Engineering (TdSE), 2021

Gefördert durch:



Bundesministerium
für Wirtschaft
und Klimaschutz

aufgrund eines Beschlusses
des Deutschen Bundestages

- ▶ Several industry players have recently started expanding services implemented by “automated vehicles”
- ▶ Safety remains key question
 - ▶ Needs to be **built-in**, not **bolt-on**!
- ▶ “**How safe is safe enough?**” is still not fully answered.



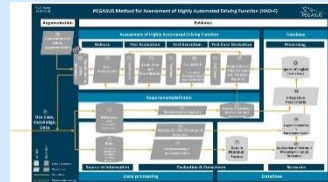
VV-METHODS PEGASUS family – Publicly-funded projects in Germany

- ▶ The **PEGASUS Family** focuses on development / testing methods and tools for AD systems on highways and in urban environments

PEGASUS

<https://www.pegasusprojekt.de/en/home>

- Scope: **Basic methodological framework**
- Use-Case: L3/4 on highways
- Partners: 17



VV-Methods



- Scope: **Methods, toolchains, specifications for technical assurance**
- Use-Case: L4/5 in urban environments
- Partners: 23 partners
- Timeline: 07/2019 – 06/2023

SET Level 4to5



- Scope: **Simulation platform, toolchains, definitions for simulation-based testing**
- Use-Case: L4/5 in urban environments
- Partners: 20 partners
- Timeline: 03/2019 – 08/2022

+ future projects of the PEGASUS Family

2016

2019

Time →

I. Systematic control of test space

Methods to map the infinitely-complex open context onto a finite & manageable set of artifacts.



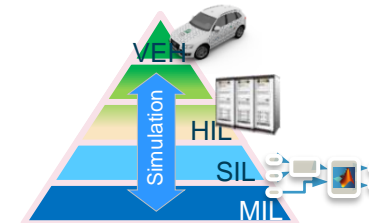
II. Consistent interfaces for systems and components

Definition of technical contracts, tests of systems and subsystems.



III. Significant shift from real-world testing to simulation

Methods for seamless testing across all test instances.

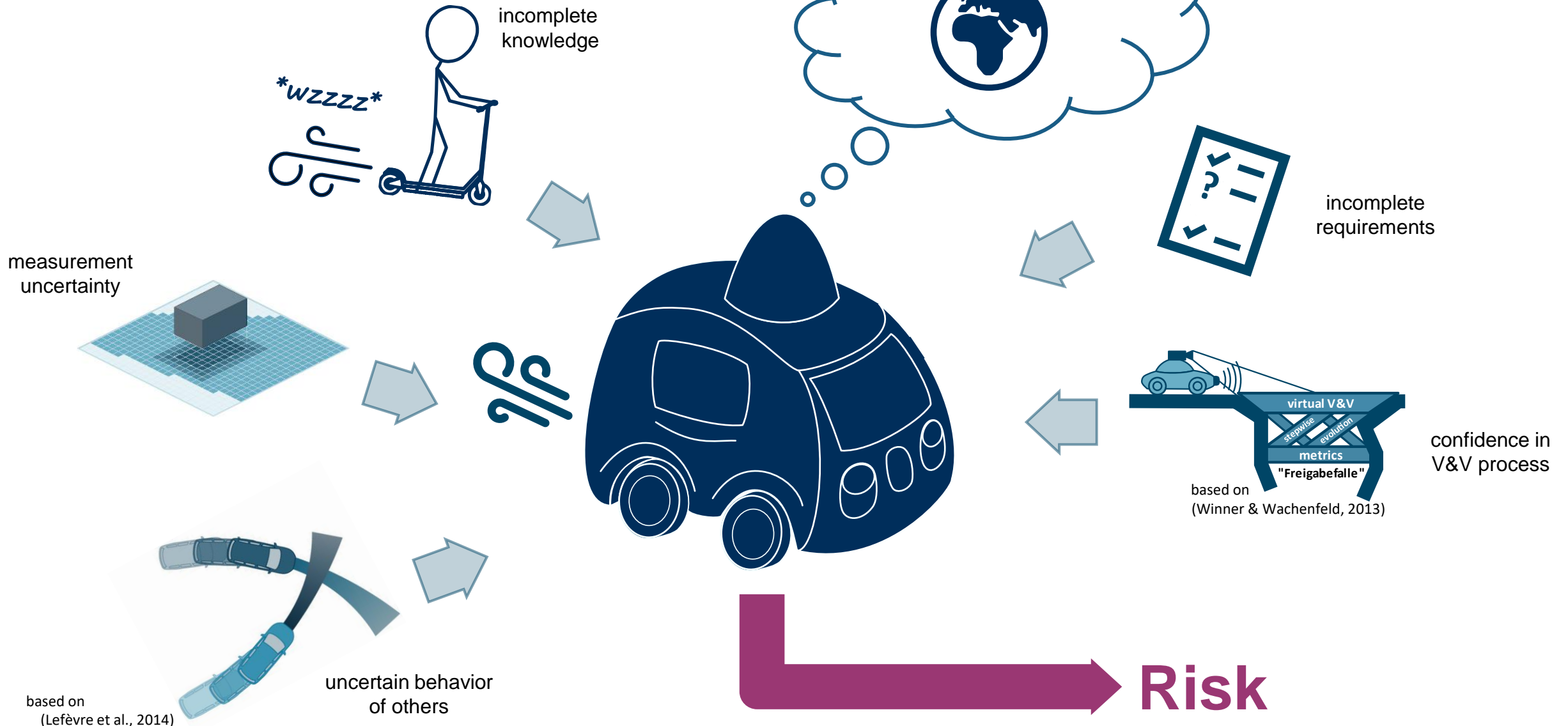


Added: IV Argumentation

- ▶ fulfillment of societal claims e.g safety, via law, standards, state of the art.



Open Context



based on
(Lefèvre et al., 2014)



How can we argue for the **absence of unreasonable risk** in an open context?

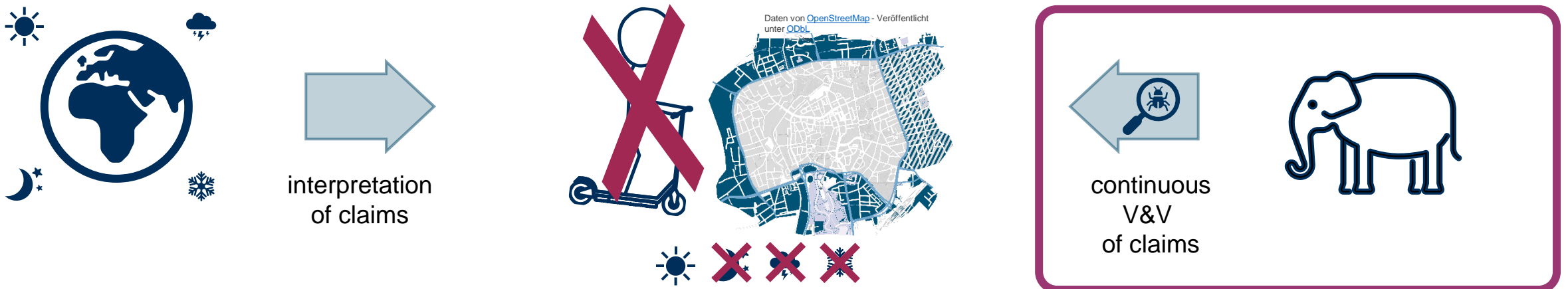
...in a comprehensible manner for a variety of stakeholders?

... to foster public trust in the technology?

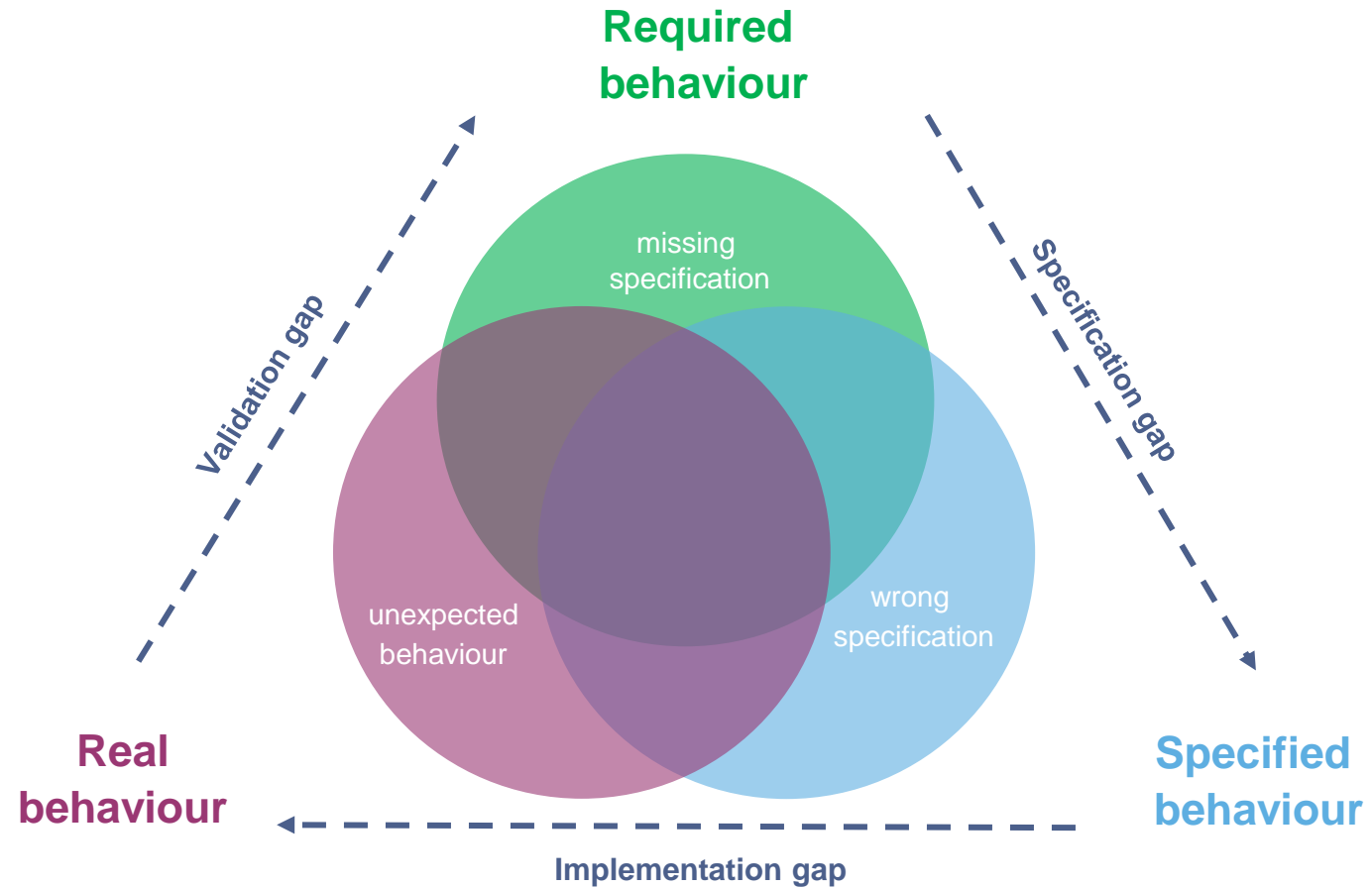
...while lacking an exact interpretation of what „reasonable“ really means?

Traceable decomposition & continuous validation of claims

- ▶ Enable argumentation that safety case will remain valid, even if **system context changes**.
- ▶ **Traceable** decomposition / interpretation of claims (assumptions)
- ▶ Continuous **post-release** verification & validation w.r.t **new findings**: Do assumptions still hold?



Perspectives of argumentation



3-Circle-Model:
Stellet, J. E.; Brade, T.; Poddey, A.; Jesenski, S.; Branz, W.:
"Formalisation and algorithmic approach to the automated driving validation problem",
IEEE Intelligent Vehicles Symposium, 3rd Workshop on Ensuring and Validating Safety for Automated Vehicles (EVSAV), Paris, France, 2019

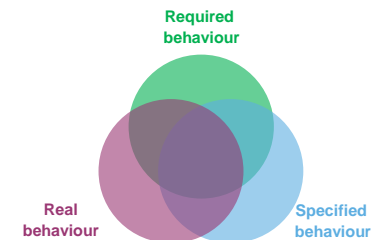
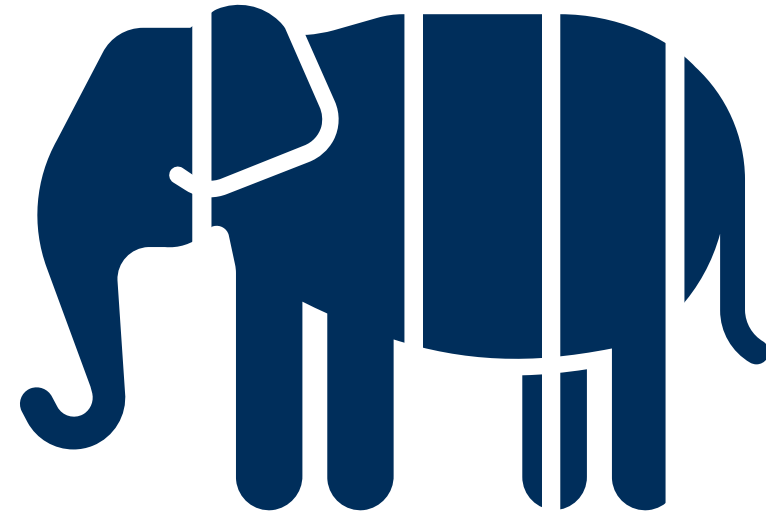
Assurance Framework

We must argue that the system in its environment is...

**Specified, verifiable and validatable
sufficiently complete & correctly**

Designed, implemented, verified and validated
correctly in a *controlled* environment

Safe under *uncontrollable* real-world conditions



(Reich, Nolte 2022)

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Capability Layer



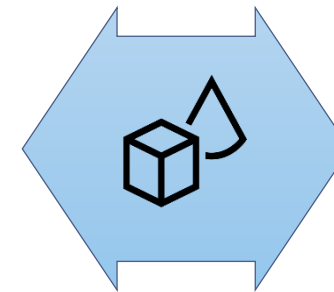
**Designed, implemented,
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Engineering Layer

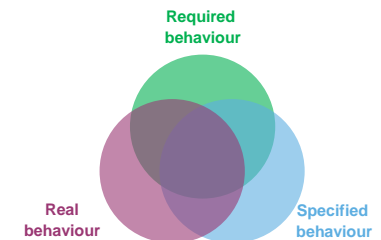
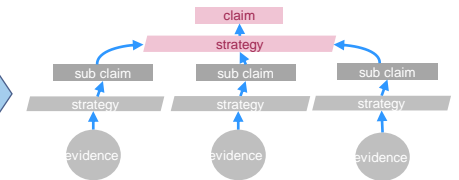


**Safe under *uncontrollable*
real-world conditions**

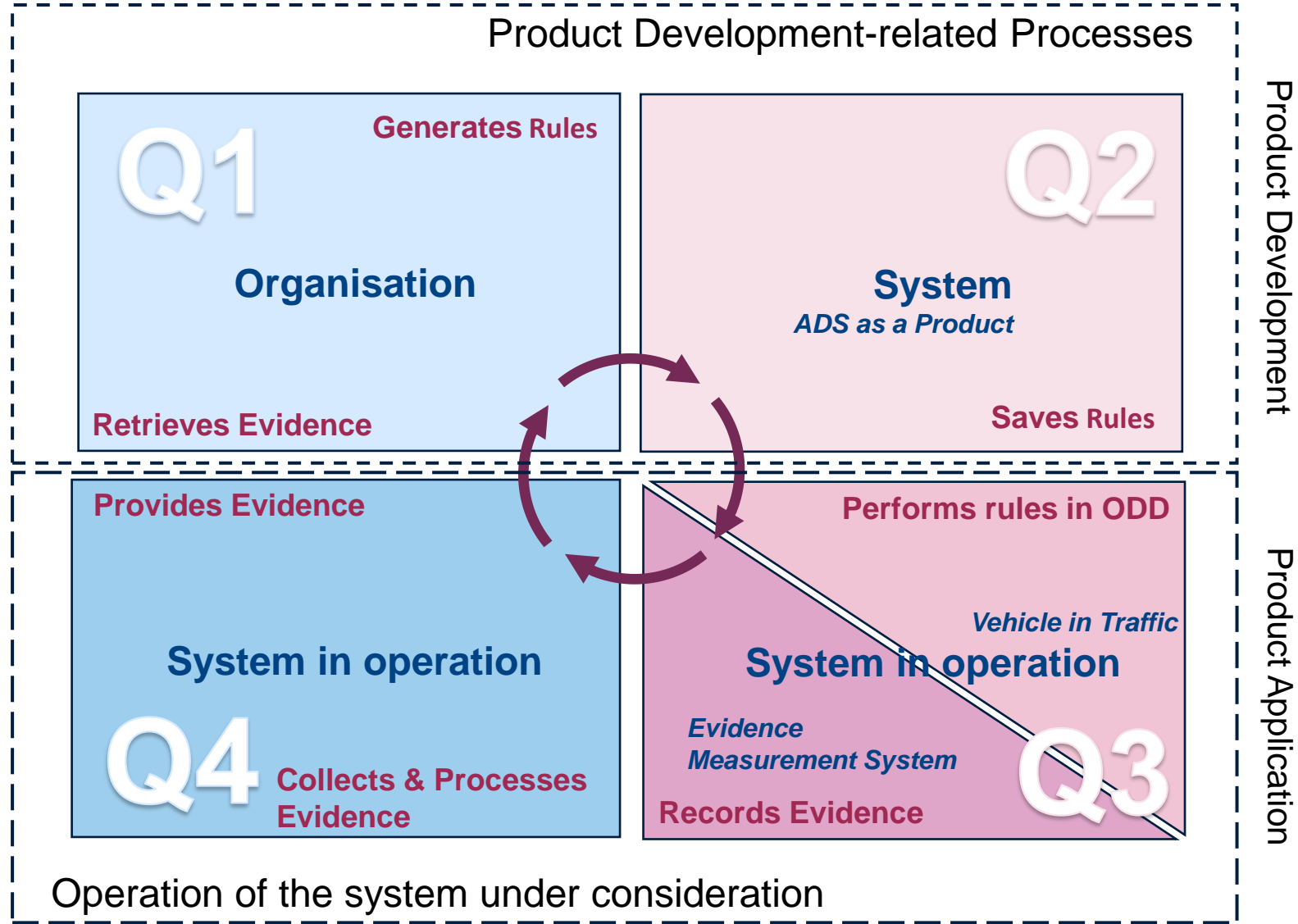
Real World Layer



Assurance
Case



Learning Driven Product Lifecycle



The Automated Driving System (ADS) is **diligently safeguarded** before release

Capabilities

Information Flow →

Q1-4

Processes with Capabilities and Activities

(Haiber et al 2021, Corell 2022)

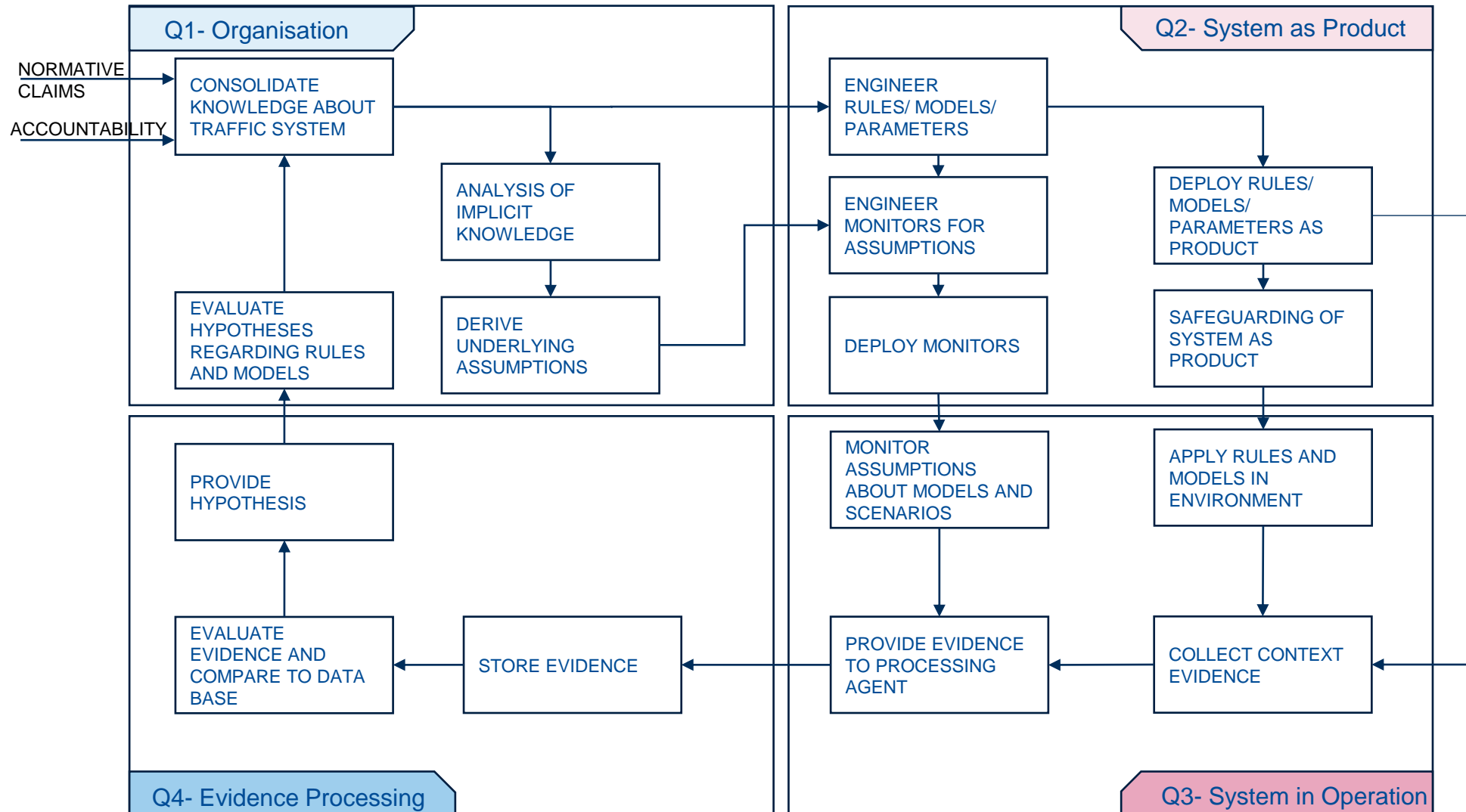
Learning Driven Product Lifecycle

“Four quadrant model”

- The Automated Driving System (ADS) is **proven safe at the time it is placed on the market**
 - We monitor the systems to further **maintain safety** in the open context
 - Monitoring can take place via a **variety of paths**, e.g.
 - via **accident data analysis**
 - via observation of traffic flow
 - via fleet and sub-fleet
 - **Monitoring must always be compliant with security and privacy laws!**
- ▶ ***We are testing during system development and not at the customer!***

Learning Driven Product Lifecycle

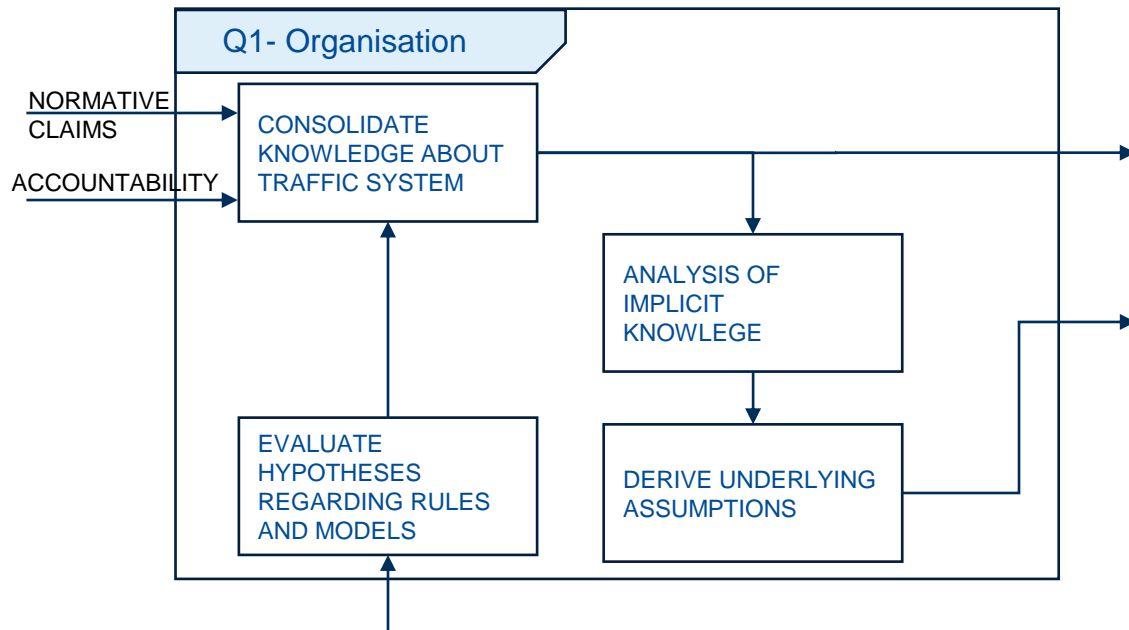
Activities in the “Four Quadrant Model” – Overview



Inspired by „Popper, Karl. Logik der Forschung. Springer Wien, 1935“

(Haiber et al 2021, Corell 2022)

Activities in the “Four Quadrant Model”– Details Q1

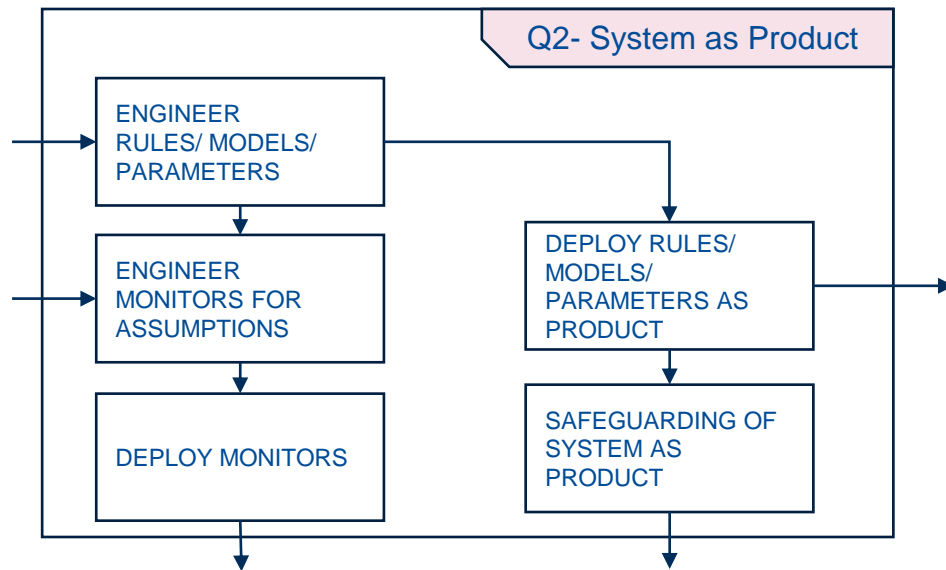


Q1 represents the Organization’s „head“ with the accountability to normatives and its will to learn

- ▶ The **knowledge** of an organization enables the realization of a system as a product.
Analyzing implicate knowledge and deriving underlying assumptions enables the organization to define monitors
- ▶ Monitors initiate a learning process about system in operation performance (reply on hypothesis)
- ▶ **Evaluating the hypothesis** regarding rules and models is the analysis activity for generating valuable knowledge for the organization

Learning Driven Product Lifecycle

Activities in the “Four Quadrant Model”– Details Q2



Q2 represents the Organization’s „body“ including the activities in development and production.

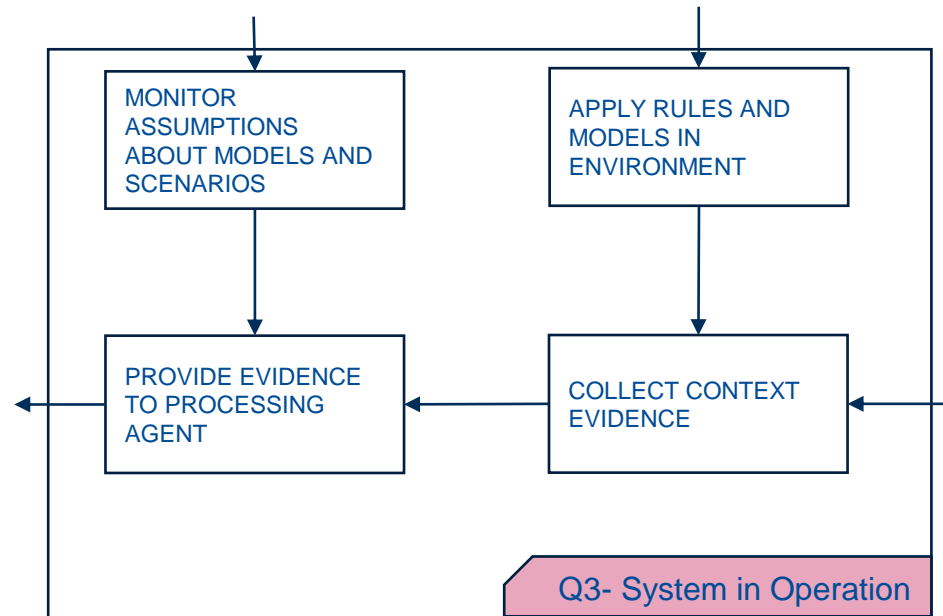
- ▶ **Engineering rules / models / parameters** is part of the design process of the system as a product
- ▶ The **rules / models / parameters** are **deployed** after design phases and before system operation
- ▶ The **engineering of monitors for assumptions** is running in parallel, based on the derived underlying assumptions
- ▶ **Monitors are deployed** before system operation
- ▶ **Safeguarding activity close the activities of Q2**

2 | Staffort Beer –Viable System Model, Cybernetics and Management, English Universities Press, Ltd., 1959

(Haiber et al 2021, Corell 2022)

Learning Driven Product Lifecycle

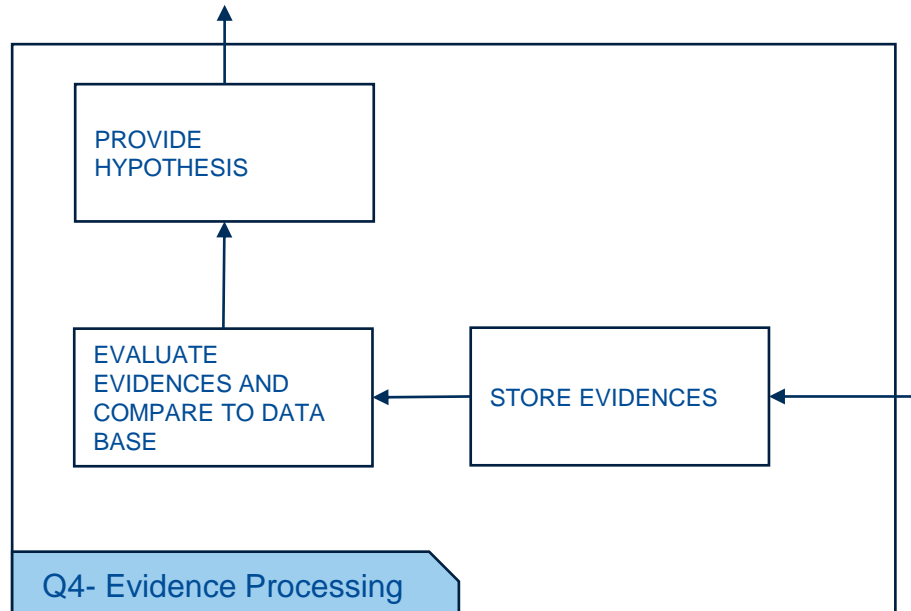
Activities in the “Four Quadrant Model” – Details Q3



Q3 represents the System in Operation (SiO) applying the implemented rules, modes and parameters

- ▶ In parallel the system in operation is **monitoring** its assumptions about models and scenarios
- ▶ During mission run, the System in Operation is **collecting** relevant evidences in Operational Environment
- ▶ Both activities, applying and monitoring are **providing** relevant evidences (data) to a processing agent

Activities in the “Four Quadrant Model” – Details Q4



Q4 represents the evidence processing agent

- ▶ The evidence processing agent is collecting and **storing** the relevant evidences

- ▶ And **evaluating** by comparing evidences to existing data within the data base.

New hypothesis are formulated, which are

- ▶ **Provided** to the organization by the agent

Learning Driven Product Lifecycle Summary

- ▶ The replacement of the human driver requires a shift of responsibility to cope with an open context
- ▶ A **dedicated learning process** supports the shift of responsibility, which allows an effective, sustainable knowledge and perspective on the world. Commonly established processes like conventional Market Observation and Quality Management are limited to cope with this challenge
- ▶ The **implementation of monitors** enables this shift of responsibility for an organization to refute or confirm assumptions made during the design process.
- ▶ Shadowing System is **one example** of implemented monitors.
- ▶ The results and new gained knowledge can be used to **improve the system**.
 This opportunity can increase the safety on fleet level, adding **positive value to the risk balance** by providing new findings and improvements to all systems in operation



(Haiber et al 2021, Corell 2022)

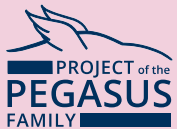
Thank you!

Marcus Nolte, *TU Braunschweig*

 nolte@ifr.ing.tu-bs.de  +49 531 391 3827

 https://www.researchgate.net/profile/Marcus_Nolte

 <https://www.linkedin.com/in/marcus-nolte-95974a143/>



**A project developed by the
VDA Leitinitiative
autonomous and connected driving**

Supported by:



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